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HOMER F. WALKER
REPORT #54 JUNE, 1976



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*The Numerical Evaluation of Maximum-Likelihood
Estimates of the Parameters for a Mixture of Normal Distributions
from Partially Identified Samples*

by

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1. Introduction.

Let π_1, \dots, π_m be populations whose multivariate observations in \mathbb{R}^n are distributed with respective normal density functions

$$p_i(x) = \frac{1}{(2\pi)^{n/2} |\Sigma_i^0|^{1/2}} e^{-\frac{1}{2}(x-\mu_i^0)^T \Sigma_i^{0-1} (x-\mu_i^0)}, \quad i = 1, \dots, m.$$

If π_0 is a given mixture of members of these populations, then observations on π_0 are distributed in \mathbb{R}^n with density function

$$p(x) = \sum_{i=1}^m \alpha_i^0 p_i(x)$$

for an appropriate set of proportions $\{\alpha_i^0\}_{i=1, \dots, m}$. These proportions necessarily satisfy $\sum_{i=1}^m \alpha_i^0 = 1$ and $\alpha_i^0 \geq 0$, $i = 1, \dots, m$. In this note, we also assume that each α_i^0 is strictly positive.

We address here the problem of numerically approximating the maximum-likelihood estimates of the parameters $\{\alpha_i^0, \mu_i^0, \Sigma_i^0\}_{i=1, \dots, m}$ determined by samples of two types. Samples of both types consist of sets $\{x_{ik}\}_{k=1, \dots, N_i}$

of independent observations on π_i , $i = 0, \dots, m$. (The sets $\{x_{ik}\}_{k=1, \dots, N_i}$, $i = 1, \dots, m$, comprise the identified observations of such samples, and such samples are said to be partially identified.) We distinguish samples of the two types according to whether the numbers N_i of identified observations contain information about the proportions α_i^0 , $i = 1, \dots, m$. If the numbers of identified observations contain no information about the proportions, then the sample is of the first type; otherwise, the sample is of the second type. The following are examples of how samples of the first and second types, respectively, might be obtained:

- (1) For $i = 0, \dots, m$, numbers N_i are arbitrarily chosen and independent observations $\{x_{ik}\}_{k=1, \dots, N_i}$ are obtained from π_i .
- (2) A number K_0 of observations are obtained from π_0 . For some $N_0 < K_0$, N_0 of these observations are left unidentified, while the remaining $K_0 - N_0$ observations are identified. For $i = 1, \dots, m$, a subset $\{x_{ik}\}_{k=1, \dots, N_i}$ of the identified observations is determined whose member observations come from π_i .

In the following, we consider likelihood equations determined by the two types of samples which are necessary conditions for a maximum-likelihood estimate. These equations, which were derived by Coberly [1], suggest certain successive-approximations iterative procedures for obtaining maximum-likelihood estimates. These procedures, which are generalized steepest ascent (deflected gradient) procedures, contain those of Hosmer [2] as a special case. Using arguments that parallel those of [3], we show that, with probability 1 as

N_0 approaches infinity (regardless of the relative sizes of N_0 and N_i , $i = 1, \dots, m$), these procedures converge locally to the strongly consistent maximum-likelihood estimates* whenever the step-size is between 0 and 2. Furthermore, the value of the step-size which yields optimal local convergence rates is bounded from below by a number which always lies between 1 and 2.

2. Samples of the first type.

We first assume that numbers $\{N_i\}_{i=0, \dots, m}$ are given and that, for $i = 0, \dots, m$, N_i independent observations $\{x_{ik}\}_{k=1, \dots, N_i}$ are drawn on π_i . The log-likelihood function for a sample of this type is

$$L_1(\theta) = \sum_{i=1}^m \sum_{k=1}^{N_i} \log p_i(x_{ik}) + \sum_{k=1}^{N_0} \log p(x_{0k}).$$

In this expression, the parameter vector θ (with components $\alpha_i, \mu_i, \Sigma_i$, $i = 1, \dots, m$) belongs to the vector space $\mathcal{A} \oplus \mathcal{M} \oplus \mathcal{S}$ defined in [3], and the density functions on the right-hand side are evaluated with the true parameter vector θ^0 (with components $\alpha_i^0, \mu_i^0, \Sigma_i^0$, $i = 1, \dots, m$) replaced by θ .

*As in [3], one can show that, given any sufficiently small neighborhood of the true parameters, there is, with probability 1 as N_0 approaches infinity (regardless of the relative sizes of N_0 and N_i , $i = 1, \dots, m$), a unique solution of the likelihood equations for either type of sample in that neighborhood, and this solution is a maximum-likelihood estimate.

Differentiating $L_1(\theta)$ and setting its partial derivatives to zero gives the likelihood equations

$$(1.a) \quad \alpha_i = A_i(\theta) \equiv \frac{\alpha_i}{N_0} \sum_{k=1}^{N_0} \frac{p_i(x_{ok})}{p(x_{ok})}$$

$$(1.b) \quad \mu_i = M_i(\theta) \equiv \left\{ \sum_{k=1}^{N_i} x_{ik} + \sum_{k=1}^{N_0} x_{ok} \frac{\alpha_i p_i(x_{ok})}{p(x_{ok})} \right\} / \left\{ N_i + \sum_{k=1}^{N_0} \frac{\alpha_i p_i(x_{ok})}{p(x_{ok})} \right\}$$

$$(1.c) \quad \Sigma_i = S_i(\theta) \equiv \left\{ \sum_{k=1}^{N_i} (x_{ik} - \mu_i)(x_{ik} - \mu_i)^T + \sum_{k=1}^{N_0} (x_{ok} - \mu_i)(x_{ok} - \mu_i)^T \frac{\alpha_i p_i(x_{ok})}{p(x_{ok})} \right\} / \left\{ N_i + \sum_{k=1}^{N_0} \frac{\alpha_i p_i(x_{ok})}{p(x_{ok})} \right\}$$

for $i = 1, \dots, m$.

We set

$$A(\theta) = \begin{pmatrix} A_1(\theta) \\ \vdots \\ A_m(\theta) \end{pmatrix}, \quad M(\theta) = \begin{pmatrix} M_1(\theta) \\ \vdots \\ M_m(\theta) \end{pmatrix}, \quad S(\theta) = \begin{pmatrix} S_1(\theta) \\ \vdots \\ S_m(\theta) \end{pmatrix}$$

and define an operator Φ_ϵ on $\mathcal{A} \oplus \mathcal{M} \oplus \mathcal{S}$ by

$$\Phi_\epsilon(\theta) = (1 - \epsilon)\theta + \epsilon \begin{pmatrix} A(\theta) \\ M(\theta) \\ S(\theta) \end{pmatrix}.$$

Clearly, for any non-zero ϵ , the likelihood equations are satisfied by a vector $\theta \in \mathcal{A} \oplus \mathcal{M} \oplus \mathcal{S}$ if and only if $\theta = \Phi_\epsilon(\theta)$.

We consider the following iterative procedure: Beginning with some starting value $\theta^{(1)}$, define successive iterates inductively by

$$(2) \quad \theta^{(j+1)} = \Phi_\epsilon(\theta^{(j)})$$

for $j = 1, 2, 3, \dots$. Our local convergence result for this iterative procedure, as stated in the introduction, follows immediately from the theorem below.

Theorem 1: With probability 1 as N_0 approaches infinity, Φ_ϵ is a locally contractive operator (in some norm on $\mathcal{A}(\Theta) \cap \mathcal{M}(\Theta)$) near the strongly consistent maximum-likelihood estimate whenever $0 < \epsilon < 2$.

In saying that Φ_ϵ is a locally contractive operator near a point $\Theta \in \mathcal{A}(\Theta) \cap \mathcal{M}(\Theta)$, we mean that there is a vector norm $\|\cdot\|$ on $\mathcal{A}(\Theta) \cap \mathcal{M}(\Theta)$ and a number λ , $0 \leq \lambda < 1$, such that

$$\|\Phi_\epsilon(\Theta') - \Theta\| \leq \lambda \|\Theta' - \Theta\|$$

whenever Θ' lies sufficiently near Θ .

Proof of Theorem 1: Let

$$\Theta = \begin{pmatrix} \bar{\alpha} \\ \bar{\mu} \\ \bar{\Sigma} \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_m \\ \mu_1 \\ \vdots \\ \mu_m \\ \Sigma_1 \\ \vdots \\ \Sigma_m \end{pmatrix}$$

be the strongly consistent maximum-likelihood estimate. We assume that

$\alpha_i \neq 0$, $i = 1, \dots, m$. (As N_0 approaches infinity, the probability is 1 that this is the case.) As in [3], it suffices to show that, with probability 1, $\forall \phi_\epsilon(0)$ converges to an operator which has operator norm less than 1 with respect to a suitable vector norm on $\mathcal{A} \otimes \mathcal{M} \otimes \mathcal{S}$.

Now

$$\forall \phi_\epsilon(0) = (1 - \epsilon)I + \epsilon \forall \begin{pmatrix} A(0) \\ M(0) \\ S(0) \end{pmatrix},$$

and we write

$$\forall \begin{pmatrix} A \\ M \\ S \end{pmatrix} = \begin{pmatrix} \forall_\alpha A & \forall_\mu A & \forall_\Sigma A \\ \forall_\alpha M & \forall_\mu M & \forall_\Sigma M \\ \forall_\alpha S & \forall_\mu S & \forall_\Sigma S \end{pmatrix}.$$

Define inner products \langle, \rangle'_i on \mathcal{M} , \langle, \rangle''_i on \mathcal{S} , and \langle, \rangle on $\mathcal{A} \otimes \mathcal{M} \otimes \mathcal{S}$ as in [3]. Setting

$$\beta_i(x) = \frac{p_i(x)}{p(x)}, \gamma_i(x) = (x - \mu_i), \delta_i(x) = [\Sigma_i^{-1}(x - \mu_i)(x - \mu_i)^T - I], K_i = N_i + \alpha_i N_0$$

for $i = 1, \dots, m$, one calculates

$$\begin{aligned} \forall_\alpha A(0) &= I - (\text{diag } \alpha_i) \frac{1}{N_0} \frac{N_0}{\Sigma} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix}^T \\ \forall_\mu A(0) &= - (\text{diag } \alpha_i) \frac{1}{N_0} \frac{N_0}{\Sigma} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \gamma_1, \cdot \rangle'_1 \\ \vdots \\ \langle \beta_m \gamma_m, \cdot \rangle'_m \end{pmatrix}^T \\ \forall_\Sigma A(0) &= - (\text{diag } \alpha_i) \frac{1}{N_0} \frac{N_0}{\Sigma} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \delta_1, \cdot \rangle''_1 \\ \vdots \\ \langle \beta_m \delta_m, \cdot \rangle''_m \end{pmatrix}^T \end{aligned}$$

$$V_{\alpha}^{-M}(0) = (\text{diag } \frac{1}{K_i} \sum_1^{N_0} \beta_i \gamma_i) - (\text{diag } \frac{\alpha_i}{K_i}) \left\{ \sum_1^{N_0} \begin{pmatrix} \beta_1 \gamma_1 \\ \vdots \\ \beta_m \gamma_m \end{pmatrix} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix}^T \right\}$$

$$V_{\mu}^{-M}(0) = (\text{diag } \frac{\alpha_i}{K_i} \sum_1^{N_0} \gamma_i \gamma_i^T \Sigma_i^{-1} \beta_i) - (\text{diag } \frac{\alpha_i}{K_i}) \left\{ \sum_1^{N_0} \begin{pmatrix} \beta_1 \gamma_1 \\ \vdots \\ \beta_m \gamma_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \gamma_1, \cdot \rangle'_1 \\ \vdots \\ \langle \beta_m \gamma_m, \cdot \rangle'_m \end{pmatrix}^T \right\}$$

$$V_{\Sigma}^{-M}(0) = (\text{diag } \frac{1}{K_i} \sum_1^{N_0} \beta_i \gamma_i \langle \delta_i, \cdot \rangle''_i) - (\text{diag } \frac{\alpha_i}{K_i}) \left\{ \sum_1^{N_0} \begin{pmatrix} \beta_1 \gamma_1 \\ \vdots \\ \beta_m \gamma_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \delta_1, \cdot \rangle''_1 \\ \vdots \\ \langle \beta_m \delta_m, \cdot \rangle''_m \end{pmatrix}^T \right\}$$

$$V_{\alpha}^{-S}(0) = (\text{diag } \frac{\Sigma_i}{K_i} \sum_1^{N_0} \beta_i \delta_i) - (\text{diag } \frac{\alpha_i \Sigma_i}{K_i}) \left\{ \sum_1^{N_0} \begin{pmatrix} \beta_1 \delta_1 \\ \vdots \\ \beta_m \delta_m \end{pmatrix} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix}^T \right\}$$

$$V_{\mu}^{-S}(0) = (\text{diag } \frac{1}{K_i} \{ -\sum_1^{N_i} [(\cdot) \gamma_i^T + \gamma_i (\cdot)^T] - \alpha_i \sum_1^{N_0} [(\cdot) \gamma_i^T + \gamma_i (\cdot)^T] \beta_i + \sum_1^{N_0} \delta_i \langle \beta_i \gamma_i, \cdot \rangle'_i \}) -$$

$$- (\text{diag } \frac{\alpha_i \Sigma_i}{K_i}) \left\{ \sum_1^{N_0} \begin{pmatrix} \beta_1 \delta_1 \\ \vdots \\ \beta_m \delta_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \gamma_1, \cdot \rangle'_1 \\ \vdots \\ \langle \beta_m \gamma_m, \cdot \rangle'_m \end{pmatrix}^T \right\}$$

$$V_{\Sigma}^{-S}(0) = (\text{diag } \frac{\Sigma_i}{K_i} \sum_1^{N_0} \beta_i \delta_i \langle \delta_i, \cdot \rangle''_i) - (\text{diag } \frac{\alpha_i \Sigma_i}{K_i}) \left\{ \sum_1^{N_0} \begin{pmatrix} \beta_1 \delta_1 \\ \vdots \\ \beta_m \delta_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \delta_1, \cdot \rangle''_1 \\ \vdots \\ \langle \beta_m \delta_m, \cdot \rangle''_m \end{pmatrix}^T \right\}$$

Here, the arguments of β_i, γ_i and δ_i can be determined from the indices of summation, e.g.,

$$\sum_1^{N_0} \beta_i \gamma_i = \sum_{k=1}^{N_0} \beta_i(x_{ok}) \gamma_i(x_{ok}) .$$

Setting

$$V = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \\ \beta_1 \gamma_1 \\ \vdots \\ \beta_m \gamma_m \\ \beta_1 \delta_1 \\ \vdots \\ \beta_m \delta_m \end{pmatrix}$$

one obtains at 0

$$\nabla \begin{pmatrix} A \\ M \\ S \end{pmatrix} = \begin{pmatrix} I & 0 & 0 \\ B_{21} & B_{22} & B_{23} \\ B_{31} & B_{32} & B_{33} \end{pmatrix} = \begin{pmatrix} (\text{diag } \frac{\alpha_i}{N_0}) & 0 & 0 \\ 0 & (\text{diag } \frac{\alpha_i}{K_i}) & 0 \\ 0 & 0 & (\text{diag } \frac{\alpha_i \gamma_i}{K_i}) \end{pmatrix} \begin{pmatrix} N_0 \\ \sum_1 V(x_{ok}) \cdot V(x_{ok}), \dots \end{pmatrix}$$

where

$$B_{21} = (\text{diag } \frac{1}{K_i} \sum_1^{N_0} \beta_i \gamma_i)$$

$$B_{22} = (\text{diag } \frac{\alpha_i}{K_i} \sum_1^{N_0} \gamma_i \gamma_i^T \Sigma_i^{-1} \beta_i)$$

$$B_{23} = (\text{diag } \frac{1}{K_i} \sum_1^{N_0} \beta_i \gamma_i \langle \delta_i, \cdot \rangle_i^m)$$

$$B_{31} = (\text{diag } \frac{\sum_1}{K_i} \sum_1^{N_0} \beta_i \delta_i)$$

$$B_{32} = (\text{diag } \frac{1}{K_i} \{ - \sum_1^{N_i} [(\cdot) \gamma_i^T + \gamma_i (\cdot)^T] - \alpha_i \sum_1^{N_0} [(\cdot) \gamma_i^T + \gamma_i (\cdot)^T] \beta_i + \sum_1^{N_0} \delta_i \langle \beta_i \gamma_i, \cdot \rangle_i^1 \})$$

$$B_{33} = (\text{diag } \frac{\sum_1}{K_i} \sum_1^{N_0} \beta_i \delta_i \langle \delta_i, \cdot \rangle_i^m)$$

We have assumed that $\hat{\theta}$ is the strongly consistent maximum-likelihood estimate. Then, regardless of the relative sizes of N_i and N_0 , one can show as in [3] that, with probability 1, $\{\nabla\phi_{\hat{\theta}}(\hat{\theta}) - E(\nabla\phi_{\hat{\theta}}(\hat{\theta}))\}$ converges to zero as N_0 approaches infinity. Now

$$E\left(\nabla \begin{pmatrix} A(\hat{\theta}^0) \\ M(\hat{\theta}^0) \\ S(\hat{\theta}^0) \end{pmatrix}\right) = \begin{pmatrix} I & 0 & 0 \\ 0 & (\text{diag } \frac{\alpha_{i0}^{ON}}{K_i} I) & 0 \\ 0 & 0 & (\text{diag } \frac{\alpha_{i0}^{ON}}{K_i} I) \end{pmatrix} -$$

$$= \begin{pmatrix} (\text{diag } \alpha_i^0) & 0 & 0 \\ 0 & (\text{diag } \frac{\alpha_{i0}^{ON}}{K_i} I) & 0 \\ 0 & 0 & (\text{diag } \frac{\alpha_{i0}^{ON}}{K_i} I) \end{pmatrix} \left\{ \int_{\mathbb{R}^n} V(x) \langle V(x), \cdot \rangle p(x) dx \right\}$$

$$= B(1 - QR),$$

where

$$B = \begin{pmatrix} I & 0 & 0 \\ 0 & (\text{diag } \frac{\alpha_{i0}^{ON}}{K_i} I) & 0 \\ 0 & 0 & (\text{diag } \frac{\alpha_{i0}^{ON}}{K_i} I) \end{pmatrix}$$

$$Q = \begin{pmatrix} (\text{diag } \alpha_i^0) & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & (\text{diag } \Sigma_i^0) \end{pmatrix}$$

$$R = \int_{\mathbb{R}^n} V(x) \langle V(x), \cdot \rangle p(x) dx.$$

It was shown in [3] that QR is positive-definite and symmetric with operator norm less than 1 with respect to the inner product $\langle \cdot, Q^{-1} \cdot \rangle$ on $\mathcal{X} \oplus \mathcal{M} \oplus \mathcal{S}$. It follows that $I - QR$ is positive-definite and symmetric with norm less than 1 with respect to $\langle \cdot, Q^{-1} \cdot \rangle$. Since B and Q commute, $\langle \cdot, Q^{-1} B^{-1} \cdot \rangle$ is an inner product on $\mathcal{X} \oplus \mathcal{M} \oplus \mathcal{S}$, and one sees that $\langle W, Q^{-1} W \rangle \leq \langle W, Q^{-1} B^{-1} W \rangle$ for $W \in \mathcal{X} \oplus \mathcal{M} \oplus \mathcal{S}$. Consequently, $B(I - QR)$ is positive-definite and symmetric with norm less than 1 with respect to the inner product $\langle \cdot, Q^{-1} B^{-1} \cdot \rangle$. One concludes that

$$E(\nabla \Phi_{\epsilon}(\theta^0)) = (1 - \epsilon)I + \epsilon E\left(\nabla \begin{pmatrix} A(\theta^0) \\ M(\theta^0) \\ S(\theta^0) \end{pmatrix}\right)$$

has norm less than 1 with respect to $\langle \cdot, Q^{-1} B^{-1} \cdot \rangle$ whenever $0 < \epsilon < 2$.

This completes the proof of the theorem.

We remark that, reasoning as in [3], one may determine a particular value of ϵ (the "optimal ϵ ") which yields, with probability 1 as N_0 approaches infinity, the fastest asymptotic uniform rates of local convergence of the iterative procedure (2) near θ . This optimal ϵ is given by

$$\epsilon = \frac{2}{2 - (\tau + \rho)}$$

where ρ and τ are, respectively the largest and smallest eigenvalues of $B(I - QR)$ regarded as an operator on $\mathcal{E} \oplus \mathcal{M} \oplus \mathcal{S}$ (\mathcal{E} is the subspace of \mathcal{C} whose components sum to zero.) Since ρ and τ lie between zero and 1, one sees that the optimal ϵ is always greater than 1. If the component populations are "widely separated," then ρ and τ are near zero and,

hence, the optimal ϵ is near 1. If two or more of the component populations are nearly indistinguishable and if N_0 is large relative to the N_i 's, then τ is near zero, and the optimal ϵ cannot be much smaller than 2.

3. Samples of the second type.

We now assume that K_0 observations are obtained from the mixture population π_0 , and that, for some $N_0 < K_0$, N_0 of these observations are left unidentified, while the remaining $K_0 - N_0$ observations are identified. For $i = 1, \dots, m$, let $\{x_{ik}\}_{k=1, \dots, N_i}$ denote the subset of the identified observations which come from π_i , and let $\{x_{ok}\}_{k=1, \dots, N_0}$ be the set of unidentified observations from π_0 . The log-likelihood function for this sample is

$$\begin{aligned} L_2(\theta) &= \log \left\{ \frac{(\sum_{i=1}^m N_i)!}{N_1! \dots N_m!} \alpha_1^{N_1} \dots \alpha_m^{N_m} \right\} + \sum_{i=1}^m \sum_{k=1}^{N_i} \log p_i(x_{ik}) + \sum_{k=1}^{N_0} \log p(x_{ok}) \\ &= \log \left\{ \frac{(\sum_{i=1}^m N_i)!}{N_1! \dots N_m!} \right\} + \sum_{i=1}^m \sum_{k=1}^{N_i} \log [\alpha_i p_i(x_{ik})] + \sum_{k=1}^{N_0} \log p(x_{ok}). \end{aligned}$$

Differentiating L_2 and setting its partial derivatives to zero gives the likelihood equations

$$(3.a) \quad \alpha_i = \tilde{A}_i(\theta) \equiv \frac{N_i}{K_0} + \frac{\alpha_i}{K_0} \sum_{k=1}^{N_0} \frac{p_i(x_{ok})}{p(x_{ok})}$$

$$(3.b) \quad \mu_i = M_i(\theta)$$

$$(3.c) \quad \Sigma_i = S_i(\theta)$$

for $i = 1, \dots, m$.

We set

$$\tilde{A}(\theta) = \begin{pmatrix} \tilde{A}_1(\theta) \\ \vdots \\ \tilde{A}_m(\theta) \end{pmatrix}$$

and define an operator $\tilde{\Phi}_\epsilon$ on $\mathcal{A}(\theta) \times \mathcal{B}$ by

$$\tilde{\Phi}_\epsilon(\theta) = (1 - \epsilon)\theta + \epsilon \begin{pmatrix} A(\theta) \\ M(\theta) \\ S(\theta) \end{pmatrix}.$$

Our iterative procedure is the following: Beginning with some starting value $\theta^{(1)}$, define successive iterates inductively by

$$(4) \quad \theta^{(j+1)} = \tilde{\Phi}_\epsilon(\theta^{(j)})$$

for $j = 1, 2, 3, \dots$. As before, the desired local convergence result for this iterative procedure follows from the theorem below.

Theorem 2: With probability 1 as N_0 approaches infinity, $\tilde{\Phi}_\epsilon$ is a locally contractive operator (in some norm on $\mathcal{A}(\theta) \times \mathcal{B}$) near the strongly consistent maximum-likelihood estimate whenever $0 < \epsilon < 2$.

Proof of Theorem 2: If θ is the strongly consistent maximum-likelihood estimate, then, as before, it suffices to show that, with probability 1, $\tilde{\Phi}_\epsilon(\theta)$ converges as N_0 approaches infinity to an operator which has operator norm less than 1 with respect to some vector norm on $\mathcal{A}(\theta) \times \mathcal{B}$.

Proceeding as before, one sees that

$$V_{\alpha} \tilde{A}(\Theta) = (\text{diag } (1 - \frac{N_i}{\alpha_i K_0})) - (\text{diag } \frac{\alpha_i}{K_0}) \left\{ \sum_{l=1}^{N_0} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix}^T \right\}$$

$$V_{\mu} \tilde{A}(\Theta) = -(\text{diag } \frac{\alpha_i}{K_0}) \left\{ \sum_{l=1}^{N_0} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \gamma_1, \cdot \rangle_1 \\ \vdots \\ \langle \beta_m \gamma_m, \cdot \rangle_m \end{pmatrix}^T \right\}$$

$$V_{\Sigma} \tilde{A}(\Theta) = -(\text{diag } \frac{\alpha_i}{K_0}) \left\{ \sum_{l=1}^{N_0} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_m \end{pmatrix} \begin{pmatrix} \langle \beta_1 \delta_1, \cdot \rangle_1'' \\ \vdots \\ \langle \beta_m \delta_m, \cdot \rangle_m'' \end{pmatrix}^T \right\}$$

The remaining Fréchet derivatives, i.e., the derivatives at Θ of M and S with respect to $\bar{\alpha}$, $\bar{\mu}$, and $\bar{\Sigma}$, are unchanged, except that K_i must be replaced by $\alpha_i K_0$ wherever it appears.

One obtains at Θ

$$(4) \quad V \begin{pmatrix} \tilde{A} \\ M \\ S \end{pmatrix} = \begin{pmatrix} (\text{diag}(1 - \frac{N_i}{\alpha_i K_0})) & 0 & 0 \\ \tilde{B}_{21} & \tilde{B}_{22} & \tilde{B}_{23} \\ \tilde{B}_{31} & \tilde{B}_{32} & \tilde{B}_{33} \end{pmatrix} - \begin{pmatrix} (\text{diag } \frac{\alpha_i}{K_0}) & 0 & 0 \\ 0 & \frac{1}{K_0} I & 0 \\ 0 & 0 & (\text{diag } \frac{\Sigma_i}{K_0}) \end{pmatrix} \left\{ \sum_{k=1}^{N_0} V(x_{0k}) \langle V(x_{0,k}), \cdot \rangle \right\}$$

In this expression, each \tilde{B}_{jk} is the same as the corresponding B_{jk} defined

previously, except that each K_1 in the latter is replaced by $\alpha_1 K_0$ in the former. One verifies that, with probability 1 as N_0 approaches infinity, (4) has the same limit as $\tilde{B}(I-QR)$, where Q and R are as before and $\tilde{B} = \frac{N_0}{K_0} I$. Repeating our earlier reasoning, one verifies that $\tilde{B}(I-QR)$ is positive-definite and symmetric with norm less than 1 with respect to the inner product $\langle \cdot, Q^{-1} \tilde{B}^{-1} \cdot \rangle$. Hence

$$\tilde{V}\tilde{\Phi}_\epsilon(\Theta) = (1 - \epsilon) + \epsilon \tilde{V} \begin{pmatrix} \tilde{A}(\Theta) \\ M(\Theta) \\ S(\Theta) \end{pmatrix}$$

converges to an operator which has norm less than 1 with respect to $\langle \cdot, Q^{-1} \tilde{B}^{-1} \cdot \rangle$ whenever $0 < \epsilon < 2$. This completes the proof of the theorem.

The remarks concerning the "optimal ϵ " at the conclusion of the preceding section are valid here verbatim.

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